

Rafael F. Cunha

University Lecturer Ph.D. Candidate

Brazilian

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Scientific interests

- Machine Learning
- Control Theory
- Game Theory
- Markov Process

Programming Skills

Matlab, Python, Git Numpy, Pandas PyTorch, TensorFlow

Languages

English C1 Dutch B1 Portuguese Native

Soft Skills

- Critical thinking
- Problem-solving
- \circ Teamwork
- Willingness to learn

Hobbies

- Playing acoustic guitar
- Biking in the countryside
- Walking in the park with my dog

Experience

Apr. 2023 – current Lecturer at University of Groningen

• Lecturer Artificial Intelligence: Development of courses for the AI curriculum, along with supervision of master's and bachelor's students enrolled in thesis projects within the AI department.

Sept. 2018 - current PhD Candidate at University of Groningen

• **Multi-agent Reinforcement Learning**: Development and convergence analysis of multi-agent **machine learning** algorithms that are able to transfer knowledge between different tasks.

• **Reinforcement Learning and autonomous vehicles**: Application of reinforcement learning algorithms, that is, an **Artificial Intelligence** technique, to reduce the fuel consumption of longitudinal platoon systems.

• Game Theory and Markov Process: Study of a general case of imitation dynamics where the structure of the game and the imitation mechanisms change in time according to a continuous-time Markov jump process.

Sept. 2019 – Sept. 2022 Teaching assistant at University of Groningen

 Daily supervisor of master and bachelor students enrolled in their thesis projects.
 Total of five projects, one each academic semester, in the fields of reinforcement learning and stochastic process.

• Tutorial classes for the course "Modelling and Analysis of Complex Networks".

Feb. 2018 – Aug. 2018 Teaching assistant at UNICAMP

• Exercise classes and tutoring for the course "Linear Systems Analysis".

Aug. 2009 – Feb. 2017 Petroleum Engineer at PETROBRAS, Brazil

• **2011 - 2017 Reservoir Engineering**: On-shore oil field management and reservoir simulations.

2010 - 2011: Production and Artificial oil lift design: Developing projects to equipping, monitoring and resolving failures of wells in on-shore oil fields.
2009 - 2010 Petrobras Graduate program: Petroleum Engineer Course with specialization in Production and Reservoirs, with a workload of 1800 hours.

Abr. 2008 – Nov. 2008 Intern at Atmos Sistemas (ATMOS), Brazil o Development of a two-axis controller for a weather radar.

Abr. 2006 – Jul. 2006 Intern at Kuka Roboter Gmbh (KUKA), Germany Identification and analysis of an industrial robot's elastic model.

Education

Sept. 2018 – current. PhD Candidate

Faculty of Science and Engineering, DTPA, University of Groningen Transfer learning in multi-agent reinforcement learning problems.

Mar. 2017 – Aug. 2018 Masters in Electrical Engineering

University of Campinas (UNICAMP), Campinas - Brazil

Thesis: Robust partial sampled-data state feedback control of Markov jump linear systems

Feb. 2003 – Dec. 2008. Bachelor in Electronic Engineering

Technological Institute of Aeronautics (ITA), São José dos Campos – Brazil Thesis: Development of a two-axis controller for radars

Courses / Certifications

- \circ Deep Learning Specialization Coursera Nov/2022
- \circ Machine Learning Specialization Coursera Sep/2022
- Eastern European Machine Learning Summer School Jul/2022
- \circ Dutch Institute of Systems and Control (DISC) Educational Program Sep/2020

Publications

- R. F. Cunha, T. R. Gonçalves, V. S. Varma, S. E. Elayoubi and M. Cao, "Reducing fuel consumption in platooning systems through reinforcement learning," in 6th IFAC Conference on Intelligent Control and Automation Sciences, 2022.
- R. F. Cunha, L. Zino, and M. Cao, "On imitation dynamics in population games with Markov switching," in 2021 European Control Conference.
- R. F. Cunha, G. W. Gabriel, and J. C. Geromel, "Robust partial sampled-data state feedback control of Markov jump linear systems," in *International Journal of Systems Science*, 50(11), 2142-2152, 2019.
- R. F. Cunha, G. W. Gabriel, and J. C. Geromel, "Partial Sampled-Data State Feedback Control of Markov Jump Linear Systems," in 9th IFAC Symposium on Robust Control Design, 2018.